L Number	Hits	Search Text	DB	Time stamp
15	113		USPAT;	2004/11/08 11:39
			US-PGPUB;	
			EPO; JPO;	
	1		DERWENT	
16	115	427/435.ccls. and (rotat\$6)	USPAT;	2004/11/08 11:39
			US-PGPUB;	
			EPO; JPO;	
17	6	427/435.ccls. and (rotat\$6) near3	DERWENT USPAT;	2004/11/08 11:40
		substrate	US-PGPUB;	2004/11/08 11:40
			EPO; JPO;	
			DERWENT	
18	11	427/435.ccls. and (mov\$3) near3 substrate	USPAT;	2004/11/08 11:52
İ			US-PGPUB;	
	-		EPO; JPO;	
19	30	427/435.ccls. and cleaning adj solution	DERWENT	2004/11/00 12 20
		42//433.ccis. and cleaning adj solution	USPAT; US-PGPUB;	2004/11/08 13:39
			EPO; JPO;	
			DERWENT	
20	2	427/435.ccls. and bath adj turnover	USPAT;	2004/11/08 11:59
			US-PGPUB;	
			EPO; JPO;	
21	0	127/136 cala and hath and hath	DERWENT	0004/33/33
21		427/436.ccls. and bath adj turnover	USPAT;	2004/11/08 11:59
			US-PGPUB; EPO; JPO;	
			DERWENT	
22	3	427/43\$.ccls. and bath adj turnover	USPAT;	2004/11/08 11:59
7			US-PGPUB;	
			EPO; JPO;	
	524		DERWENT	
_	524	articulat\$ near mechanical	USPAT;	2004/11/05 13:34
•		•	US-PGPUB; EPO; JPO;	
			DERWENT	· .
_	9	articulat\$ near electromechanical	USPAT;	2004/11/04 13:53
			US-PGPUB;	
			EPO; JPO;	
_	3549	/immoraça dinca) with /automotors	DERWENT	
	3349	(immers\$3 dip\$3) with (automat\$5)	USPAT;	2004/11/04 14:16
			US-PGPUB; EPO; JPO;	
			DERWENT	
***	3	((immers\$3 dip\$3) with (automat\$5)) same	USPAT;	2004/11/04 13:55
		electromechanical	US-PGPUB;	
			EPO; JPO;	
	. 11	("4414350" "4994521" "5247863" "5061523"	DERWENT	2004/11/04/11
·	**	"5500460").pn.	USPAT; US-PGPUB;	2004/11/04 13:56
		3300100 7.pm.	EPO; JPO;	
			DERWENT	
_	5	("4414350" "4994521" "5247863" "5061523"	USPAT;	2004/11/04 14:32
		"5500460").pn. and immers\$3	US-PGPUB;	
			EPO; JPO;	
_	22	articulaté noan machanical and '	DERWENT	0001/11/15
	24	articulat\$ near mechanical and immers\$	USPAT;	2004/11/04 14:07
i			US-PGPUB; EPO; JPO;	
			DERWENT	
-	1167	118/423.ccls.	USPAT;	2004/11/04 14:07
			US-PGPUB;	
			EPO; JPO;	,
	,	110/422 0010 0010 000	DERWENT	
	4	118/423.ccls. and electromechanical	USPAT;	2004/11/04 14:08
			US-PGPUB;	
	}		EPO; JPO; DERWENT	
			I STIMATIAT	

,				,
_	26	118/423.ccls. and robot	USPAT;	2004/11/04 14:15
	:		US-PGPUB; EPO; JPO;	
			DERWENT	
-	12	1 1000000 1500242	USPAT	2004/11/04 14:10
		"4933119" "5337880" "5597609" "5679756" "5750060" "5750156"		
		"6008296" "6015512" "6033718").PN.		
_	6	4911098.URPN.	USPAT	2004/11/04 14:13
_	3	1 420,000 /.EN.	USPAT	2004/11/04 14:14
-	183	(immers\$3 dip\$3) with (automat\$5) and robot\$5	USPAT;	2004/11/04 14:26
		100000	US-PGPUB; EPO; JPO;	
			DERWENT	
-	136	The state of the s	USPAT;	2004/11/04 14:33
		robot	US-PGPUB;	
			EPO; JPO; DERWENT	
_	47	((immers\$3 dip\$3) with (automat\$5) and	USPAT;	2004/11/04 14:26
		robot\$5) not ((immers\$3 dip\$3) with	US-PGPUB;	2004/11/04 14.20
		(automat\$5) and robot)	EPO; JPO;	
_	0	("4414350" "4994521" "5247863" "5061523"	DERWENT	0004/22/04 24 25
		"5500460").pn. and phenolic	USPAT; US-PGPUB;	2004/11/04 14:32
			EPO; JPO;	
_	7	/ !! / / 1 / 2 5 0 !! !! / 0 0 / 5 0 1 !! !! 5 0 ! = 5 0 !!	DERWENT	
-	/	("4414350" "4994521" "5247863" "5061523" "5500460").pn. and acid	USPAT;	2004/11/04 14:33
		5500400).pii. and acid	US-PGPUB; EPO; JPO;	
			DERWENT	
-	356	The state of the s	USPAT;	2004/11/04 14:33
		robot	US-PGPUB;	
			EPO; JPO;	
_	1	("4414350" "4994521" "5247863" "5061523"	DERWENT USPAT;	2004/11/04 14:41
6		"5500460").pn. and dry adj film	US-PGPUB;	2004/11/04 14:41
		•	EPO; JPO;	
_	2	6521687.pn. and phenolic	DERWENT	
		oszioor.pii. and phenolic	USPAT; US-PGPUB;	2004/11/04 15:24
		,	EPO; JPO;	
		600/64	DERWENT	
_	3	623/64.ccls. and (immers\$4 dip\$5)	USPAT;	2004/11/04 15:27
			US-PGPUB;	
		·	EPO; JPO; DERWENT	
-	25	700/245\$.ccls. and (immers\$4 dip\$5)	USPAT;	2004/11/04 15:28
			US-PGPUB;	
			EPO; JPO;	
_	6	901/14\$.ccls. and (immers\$4 dip\$5)	DERWENT USPAT;	2004/11/04 15:34
			US-PGPUB;	
			EPO; JPO;	
_	7	4827954.URPN.	DERWENT	2004/11/04 15 55
-	1726	(immers\$4 dip\$5) near4 (robot\$3 automat\$3)	USPAT;	2004/11/04 15:30 2004/11/04 15:36
			US-PGPUB;	2004/11/04 13:30
			EPO; JPO;	
_	0	electromechanical near3 robot adj arm with	DERWENT	2004/11/24 15
	'	(immers\$3 or dip\$4)	USPAT; US-PGPUB;	2004/11/04 15:41
		* ·· · · · ·	EPO; JPO;	İ
_	204		DERWENT	
	294	(electromechanical robot adj arm) with (immers\$3 or dip\$4)	USPAT;	2004/11/04 15:41
		(*************************************	US-PGPUB;	
			EPO; JPO; DERWENT	
_	0	((electromechanical robot adj arm) with	USPAT;	2004/11/04 15:41
		(immers\$3 or dip\$4)) and 118/423,50\$.ccls.	US-PGPUB;	
			EPO; JPO;	
			DERWENT	

1					
	_	9	((electromechanical robot adj arm) with (immers\$3 or dip\$4)) and 118/\$.ccls.	US-PGPUB;	2004/11/04 15:41
113	_	3		DERWENT USPAT;	2004/11/04 15:41
14 156/345.32.ccls. and (immers%) or dip\$4) EPO; JPO; DRMENT USPAT; USPAT	_	113	(mechanical robot adj arm) with (immers\$3	EPO; JPO; DERWENT USPAT;	2004/11/04 15:54
140 156/345.32.ccls. 156/345.ccls. 156/345.ccls	_	14		EPO; JPO; DERWENT	2004/11/04 15 55
140 156/345.32.ccls.			1507545.02.0015. and (Indue:1555 Of Gip\$4)	US-PGPUB; EPO; JPO;	2004/11/04 15:55
39 427/43\$.ccls. and robot	_	140	156/345.32.ccls.	USPAT; US-PGPUB;	2004/11/04 15:58
1100 427/435.ccls. DERWENT USPAT; USPERUS; EPG; UPG; EPG; UPG; EPG; UPG; EPG; UPG; EPG; UPG; EPG; UPG; DERWENT USPAT; USP-GPUB; EPG; UPG; UPG; UPG; UPG; UPG; UPG; UPG; U	_	39	427/43\$.ccls. and robot	DERWENT USPAT; US-PGPUB;	2004/11/05 10:36
138 427/435.ccls. and (autom\$6) DERWENT USPAT; US-PGPUB; EPO; JPO; DERWENT USPAT; USPAT	-	1100	427/435.ccls.	DERWENT USPAT;	2004/11/05 10:37
FPO; JPO; DERMENT USPAT; US-PGPUB; EPO; JPO; DERMENT USPAT; US-PGPUB; EPO; JPO; DERMENT USPAT; USP	_	138	427/435.ccls. and (autom\$6)	DERWENT USPAT;	2004/11/08 11:38
Continue	_	60	427/435.ccls. and (automat\$6)	EPO; JPO; DERWENT USPAT;	2004/11/05 10:41
15	_	6	/ Too Too I and / CICCELOMICCHAMOS	DERWENT USPAT; US-PGPUB;	2004/11/08 11:39
DERWENT USPAT; autodeposs6 immers4) and (427/43\$.ccls. 82 (electromechan\$3 robot\$3) and (dip\$3 autodeposs6 immer\$4) and (427/43\$.ccls. 18/4\$.ccls.) 82 (electromechan\$3 robot\$3) and (dip\$3 autodepos\$6 immer\$4) and (427/43\$.ccls. 118/4\$.ccls.) and (coat\$3) 83 (electromechan\$3 robot\$3) and (dip\$3 autodepos\$6 immer\$4) and (vibrat\$6) 84 (electromechan\$3 robot\$3) and (dip\$3 autodepos\$6 immer\$4) and (vibrat\$6) 85 (electromechan\$3 robot\$3) with (dip\$3 autodepos\$6 immer\$4) and (427/43\$.ccls. 118/4\$.ccls.) and vibrat\$5 86 (electromechan\$3 robot\$3) with (dip\$3 autodepos\$6 immer\$4) and drip\$5 87 (electromechan\$3 robot\$3) with (dip\$3 autodepos\$6 immer\$4) and drip\$5 88 (electromechan\$3 robot\$3) with (dip\$3 autodepos\$6 immer\$4) 89 (electromechan\$3 robot\$3) with (dip\$3 autodepos\$6 immer\$4) 80 (electromechan\$3 robot\$3) with (dip\$3 autodepos\$6 immer\$4) 80 (electromechan\$3 robot\$3) with (dip\$3 autodepos\$6 immer\$4) 80 (electromechan\$3 robot\$3) with (dip\$3 autodepos\$6 immer\$4) 80 (electromechan\$3 robot\$3) with (dip\$3 autodepos\$6 immer\$4) 80 (electromechan\$3 robot\$3) with (dip\$3 autodepos\$6 immer\$4) 80 (electromechan\$3 robot\$3) with (dip\$3 autodepos\$6 immer\$4) 80 (electromechan\$3 robot\$3) with (dip\$3 autodepos\$6 immer\$4) 80 (electromechan\$3 robot\$3) with (dip\$3 autodepos\$6 immer\$4) 80 (electromechan\$3 robot\$3) with (dip\$3 autodepos\$6 immer\$4) 80 (electromechan\$3 robot\$3) with (dip\$3 autodepos\$6 immer\$4) 80 (electromechan\$3 robot\$3) with (dip\$3 autodepos\$6 immer\$4) 80 (electromechan\$3 robot\$3) with (dip\$3 autodepos\$6 immer\$4) 80 (electromechan\$3 robot\$3) with (dip\$3 autodepos\$6 immer\$4) 80 (electromechan\$3 robot\$3) with (dip\$3 autodepos\$6 immer\$4) 80 (electromechan\$3 robot\$3) with (dip\$3 autodepos\$6 immer\$4) 80 (electromechan\$3 robot\$3) with (dip\$3 autodepos\$6 immer\$4) 80 (electromechan\$3 robot\$3) with (dip\$3 autodepos\$6 immer\$4) 80 (electromechan\$3 robot\$3) with (dip\$3 autodepos\$6 immer\$4) 80 (electromechan\$3 robot\$3) autodepos\$6 immer\$4) 80 (electromechan\$3 robot\$3) autodepos\$6 immer\$4)	_	15	autodepos\$6 immer\$4) and (427/43\$.ccls.	DERWENT USPAT; US-PGPUB;	2004/11/05 11:48
S2	_	114	autodepos\$6 immer\$4) and (427/43\$.ccls.	DERWENT USPAT; US-PGPUB;	2004/11/05 11:31
- 1530 (electromechan\$3 robot\$3) and (dip\$3 autodepos\$6 immer\$4) and (vibrat\$6) - 1 (electromechan\$3 robot\$3) with (dip\$3 autodepos\$6 immer\$4) and (427/43\$.ccls. 118/4\$.ccls.) and vibrat\$5 - 36 (electromechan\$3 robot\$3) with (dip\$3 autodepos\$6 immer\$4) and drip\$5 - 536 (electromechan\$3 robot\$3) with (dip\$3 autodepos\$6 immer\$4) and drip\$5 - 536 (electromechan\$3 robot\$3) with (dip\$3 autodepos\$6 immer\$4) - 537 ((electromechan\$3 robot\$3) with (dip\$3 autodepos\$6 immer\$4) - 37 ((electromechan\$3 robot\$3) with (dip\$3 autodepos\$6 immer\$4)) with (rotat\$3 autodepos\$6 immer\$4)) with (rotat\$3 autodepos\$6 immer\$4) - 37 (electromechan\$3 robot\$3) with (dip\$3 autodepos\$6 immer\$4)) with (rotat\$3 autodepos\$6 immer\$4) - 37 (electromechan\$3 robot\$3) with (dip\$3 autodepos\$6 immer\$4)) with (rotat\$3 autodepos\$6 immer\$4) - 37 (electromechan\$3 robot\$3) with (dip\$3 autodepos\$6 immer\$4)) with (rotat\$3 autodepos\$6 immer\$4) - 37 (electromechan\$3 robot\$3) with (dip\$3 autodepos\$6 immer\$4)) with (rotat\$3 autodepos\$6 immer\$4)	_	82	autodepos\$6 immer\$4) and (427/43\$.ccls.	DERWENT USPAT; US-PGPUB;	2004/11/05 11:47
1	_	1530	(electromechan\$3 robot\$3) and (dip\$3	DERWENT USPAT; US-PGPUB;	2004/11/05 11:48
- 36 (electromechan\$3 robot\$3) with (dip\$3 utodepos\$6 immer\$4) and drip\$5 US-PGPUB; EPO; JPO; DERWENT USPAT; autodepos\$6 immer\$4) USPAT; USPAT	-	1	autodepos\$6 immer\$4) and (427/43\$.ccls.	DERWENT USPAT; US-PGPUB;	2004/11/05 11:52
- S36 (electromechan\$3 robot\$3) with (dip\$3 US-PGPUB; EPO; JPO; DERWENT USPAT; 2004/11/05 13:02 - 37 ((electromechan\$3 robot\$3) with (dip\$3 autodepos\$6 immer\$4)) with (rotat\$3 uS-PGPUB; EPO; JPO; DERWENT USPAT; US-PGPUB; EPO; JPO; DERWENT - DERWENT USPAT; 2004/11/05 13:08 - DERWENT USPAT; DERWENT	_	36	(electromechan\$3 robot\$3) with (dip\$3	DERWENT USPAT; US-PGPUB;	2004/11/05 13:09
- 37 ((electromechan\$3 robot\$3) with (dip\$3 USPAT; USPAT; US-PGPUB; EPO; JPO; DERWENT		536	<pre>(electromechan\$3 robot\$3) with (dip\$3 autodepos\$6 immer\$4)</pre>	DERWENT USPAT; US-PGPUB;	2004/11/05 13:02
DERWENT	_	37	autodepos\$6 immer\$4)) with (rotat\$3	DERWENT USPAT; US-PGPUB;	2004/11/05 13:08
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			•	
-	93	two adj coat near3 adhesive	USPAT;	2004/11/05 13:09
İ			US-PGPUB;	1
			EPO; JPO;	
	1	·	DERWENT	
, -	37	(two adj coat near3 adhesive) and (dip\$3	USPAT;	2004/11/05 13:09
		autodepos\$6 immer\$4)	US-PGPUB;	2001/11/03 13:09
			EPO; JPO;	
			DERWENT	
– ·	127	427/435.ccls. and adhesive	USPAT;	2004/11/05 13:34
	Í		US-PGPUB;	2004/11/05 15.54
			EPO; JPO;	
			DERWENT	
_	21	427/43\$.ccls. and (prevent\$) near2 drip\$4	USPAT;	2004/11/05 13:42
		(Plovemoty medile drippy	US-PGPUB;	2004/11/03 13:42
		•	EPO; JPO;	
			DERWENT	
-	0	10609116.ap.	USPAT;	2004/11/05 14-02
İ			US-PGPUB;	2004/11/05 14:02
			EPO; JPO;	
	1		DERWENT	.
- , v	7	kucera.in. and mowrey.in.	USPAT;	2004/11/05 12 42
		moviey.iii.	· ·	2004/11/05 13:43
			US-PGPUB;	
			EPO; JPO; DERWENT	
_	8	(kucera.in. mowrey.in. cowles.in.) and		2004/11/05 14 00
		(autodeposition) and (adhesive)	USPAT;	2004/11/05 14:08
		(adilesive)	US-PGPUB;	
			EPO; JPO;	
_	4	(kucera.in. mowrey.in. cowles.in.) and	DERWENT	2004/11/05 12
	1	(autodeposition) and (adhesive) and	USPAT;	2004/11/05 13:44
		autom\$6	US-PGPUB;	
		a a comp o	EPO; JPO;	
	1	2000-532680.NRAN.	DERWENT	00044045
	1	2000-002000.WKAN.	DERWENT	2004/11/05 14:09